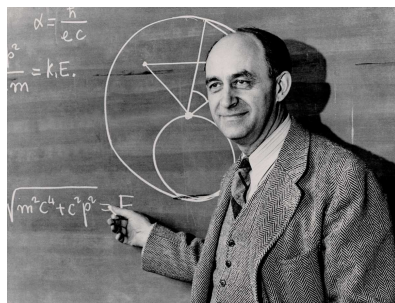




Montecarlo Methods

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The course

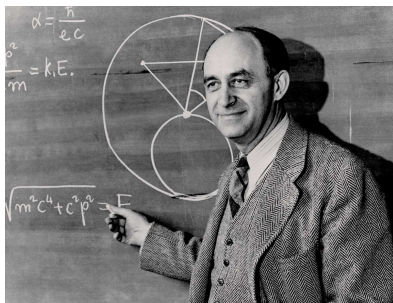


1. CM Tuesday : 9.00-12.00 (E428) **all**
2. TP Tuesday : **15.30-18.30 (E428) (29p) (French)**
3. TP Wednesday : **14.00-17.00 (E428) (30p) (English)**

The term Monte Carlo Method refers to any numerical method employing random numbers to solve a problem in a probabilistic manner.

These methods are largely used in science :

1. to simulate stochastic and deterministic processes ;
2. to perform approximate numerical estimation (integrals etc.)
3. to simulate the response of experimental apparatus
4. to find a minimum or a maximum of a function (simulated annealing)



Brief History



1. **1930s** First significant scientific application of MC : **Enrico Fermi** used it for neutron transport in fissile material. **Segre** : “Fermi took great delight in astonishing his Roman colleagues with his ”too-good-to-believe” predictions of experimental results.”
2. **1940s** Monte Carlo named by **Nicholas Metropolis and Stanislaw Ulam**
3. **1953** Algorithm for sampling any probability density **Metropolis, Rosenbluth, and Teller** (generalized by **Hastings** in 1970)
4. **1962,1974** First QMC calculations, **Kalos, Levesque, Verlet.**

Program of the Course



1. Integral Estimation with Monte Carlo Methods
2. Statistical Physics and Equilibrium Thermodynamics (Canonical Ensemble)
3. The Montecarlo Method
4. Applications
 - (a) Ising model
 - (b) Simulated annealing
 - (c) etc

Integration of a function in 1d



One of the most employed deterministic methods consists in dividing the interval of definition of a function $f(x)$ in small sub-intervals :

Simple approximation

The most simple estimation of the integral of a function f over the interval $[a, b]$ can be obtained by estimating the surface of a rectangle of sides $(b - a)$ and $f(a)$ (the inferior limit of the function)

$$\int_a^b dx f(x) \approx (b - a) f(a) =: F_1 .$$

In order to estimate the error done in such an estimation of the real integral, we use of the Taylor expansion of f around a

$$f(x) = f(a) + (x - a) f'(a) + \dots ,$$

therefore

$$\int_a^b dx f(x) = \int_a^b dx [f(a) + (x - a) f'(a)] + \dots = F_1 + \frac{(b - a)^2}{2} f'(a) + \dots .$$

The error made with the approximation F_1 is proportional to $(b - a)^2$.

Method of the median point



To obtain a better estimation it is sufficient to consider the median point of the interval $[a, b]$ to estimate the integral of f :

$$\int_a^b dx f(x) \approx (b - a) f\left(\frac{a + b}{2}\right) =: F_2 .$$

By considering the Taylor expansion around the point $x_m = \frac{a+b}{2}$

$$f(x) = f(x_m) + (x - x_m) f'(x_m) + \frac{(x - x_m)^2}{2} f''(x_m) + \dots$$

one gets

$$\begin{aligned} \int_a^b dx f(x) &= \int_a^b dx \left(f(x_m) + (x - x_m) f'(x_m) + \frac{(x - x_m)^2}{2} f''(x_m) \right) + \dots \\ &= F_2 + \frac{(b - a)^3}{24} f''(x_m) + \dots \end{aligned}$$

Now the error of the approximation F_2 is proportional to $(b - a)^3$. and if $b - a$ is small, the approximation F_2 is better than the approximation given by F_1 .

Simpson Method



By employing the lower and upper bound of the interval, as well the median point one can obtain an even better approximation of the integral :

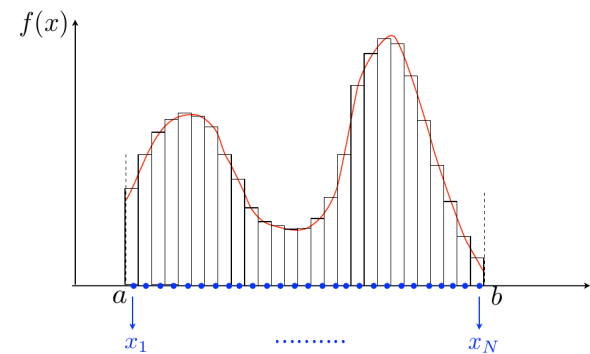
$$\int_a^b dx f(x) \approx \frac{b-a}{6} \left(f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right) =: F_3.$$

One can use once more the Taylor expansion to estimate the error done with such approximation, after very long calculus ... one gets

$$\int_a^b dx f(x) = F_3 + \frac{(b-a)^5}{2880} f^{(iv)}(\xi)$$

with $\xi \in [a, b]$.

Equidistant values



The approximations are good for **small** $b - a$, therefore one should divide the interval $[a, b]$ in small sub-intervals and estimate the integral on each of that. By taking **N intervals of the same length**,

$$\Delta x = \frac{b - a}{N}$$

with extrema $a_i := a + i \Delta x$, $b_i := a + (i + 1) \Delta x$ for $i = 0, \dots, N - 1$. Obviously, $a_0 = a$, $b_{N-1} = b$ et $a_{i+1} = b_i$. Finally, one can utilize the expressions for the approximations F1, F2 and F3, for the sub-intervals $[a_i, b_i]$.

In the case of the **method of the median point** one gets :

$$\int_a^b dx f(x) \approx \Delta x \sum_{i=0}^{N-1} f\left(a + \left(i + \frac{1}{2}\right) \Delta x\right) =: F_2(N).$$

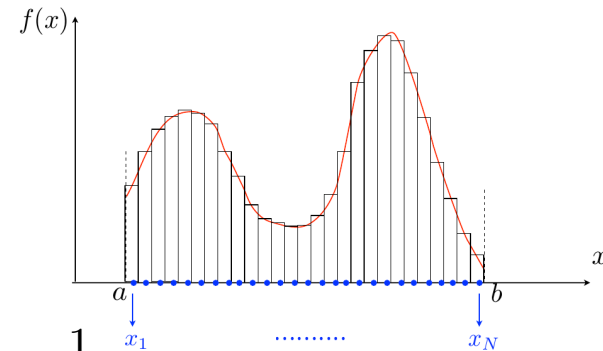
In this case, for every sub-interval the error is proportional to Δx^3 . Since we have N intervals, **the total error is proportional to** $N \Delta x^3 = (b - a)^3 / N^2 \propto 1/N^2$.

Integration errors



1. Simple approximation

$$\left| \int_a^b dx f(x) - F_1(N) \right| \propto \frac{1}{N}$$



2. Method of the median point

$$\left| \int_a^b dx f(x) - F_2(N) \right| \propto \frac{1}{N^2}$$

3. Simpson Method

$$\left| \int_a^b dx f(x) - F_3(N) \right| \propto \frac{1}{N^4}$$

Higher dimensions



Let us consider an hypercube $Q = [a_1, b_1] \times \dots \times [a_d, b_d]$ in d dimensions, in this case the d -dimensional integral can be written as

$$\int_Q d^d x f(\vec{x}) = \int_{a_d}^{b_d} dx_d \dots \int_{a_1}^{b_1} dx_1 f(x_1, \dots, x_d).$$

One can use one of the three methods described so-far, if we discretize each dimension with N points the total number of points we have is $N_T = N^d$ or otherwise

$$N = \sqrt[d]{N_T} = (N_T)^{1/d}.$$

The error for the medina point is therefore

$$\left| \int_Q d^d x f(\vec{x}) - F_2(N) \right| \propto N_T^{-2/d}.$$

The error for the simple approximation is proportional to $N_T^{-1/d}$ and for the Simpson method is proportional to $N_T^{-4/d}$

Higher dimensions



In higher dimensions one need many more N_T points to get a precise result :

1. Let us assume that $N = 100$ for each dimension and we are in $d = 10$ dimensions, therefore we must estimate the sum over $N_T = 100^{10} = 10^{20}$ points ;
2. if our computer needs 10^{-10} secs to estimate each element of the sum
3. the total CPU time required by the computer is $T \simeq 10^{10} \text{secs} \simeq 1000 \text{years}$

We need another method
Montecarlo Method

How to estimate the area of a surface



We want to estimate the area A_F of a surface $F \subset \mathbb{R}^2$ in 2 dimensions. Let us use the characteristic function χ_F of F ,

$$\chi_F(\vec{x}) = \begin{cases} 1 & \text{si } \vec{x} \in F \\ 0 & \text{si } \vec{x} \notin F \end{cases}$$

We should therefore estimate a two dimensional integral. We can approximate this integral with a so-called Riemann sum, namely

$$A_F = \int_{\mathbb{R}^2} d^2x \chi_F(\vec{x}) \approx \sum_i \chi_F(\vec{x}_i) A_i.$$

where \vec{x}_i are points in the plane, each one surrounded by a surface A_i .

One would think to use a regular distribution of the points \vec{x}_i , but this is not needed. We can use a completely random distribution

The Monte-Carlo method



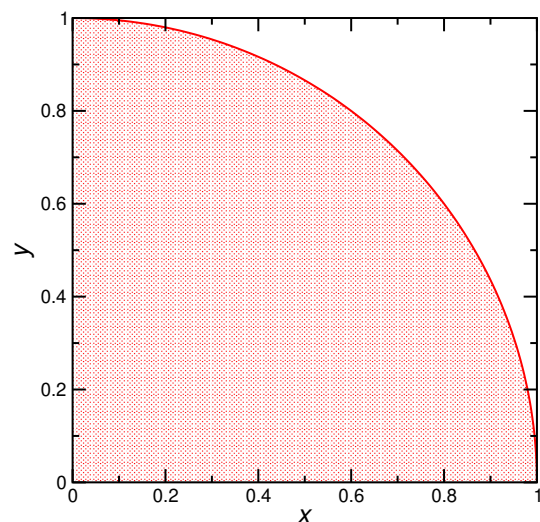
the Hit and Miss method

In practice, one should include the surface F p.-ex. within a rectangle R .

The area A_R of the rectangle is known and if we consider N points inside R , their average area is $A_i = A_R/N$.

Therefore for $F \subset R$ the area can be approximated as

$$A_F = \int_R d^2x \chi_F(\vec{x}) \approx \frac{A_R}{N} \sum_{i=1}^N \chi_F(\vec{x}_i).$$



Exercise (Estimate π with the Hit and Miss Method) :

Consider $N = 100\,000$ couples (x_i, y_i) with $x_i, y_i \in [0, 1)$. Now you should count the number of cases for which $x_i^2 + y_i^2 < 1$ and estimate the probability of having the point (x_i, y_i) inside the circle see the Figure. Estimate the error for such evaluation and compare it with $\pi/4$.

Please employ `np.random.random_sample()` .
Random generator within $[0 : 1)$ with uniform distribution.

Hit and Miss method



```
# pi and the Monte-Carlo Method
import numpy as np          # importer le module comme "np"
N=1000                      # number of points points
cnt = 0
var = 0

for i in range(0,N):
    x = np.random.random_sample() # generate the couple (x,y)
    y = np.random.random_sample()
    if x*x + y*y < 1:           # Is the couple within the circle ?
        cnt += 1                # If yes count them
        var += 1**2

moy = cnt/float(N)           # the average
var=  var/float(N) -moy*moy  # the variance
ecart = np.sqrt(var/N)      # standard deviation of the average

print "compte =", moy, "+/-", ecart
print "pi/4   =", np.pi/4
print "(error =", np.abs(moy-np.pi/4), ") "
```

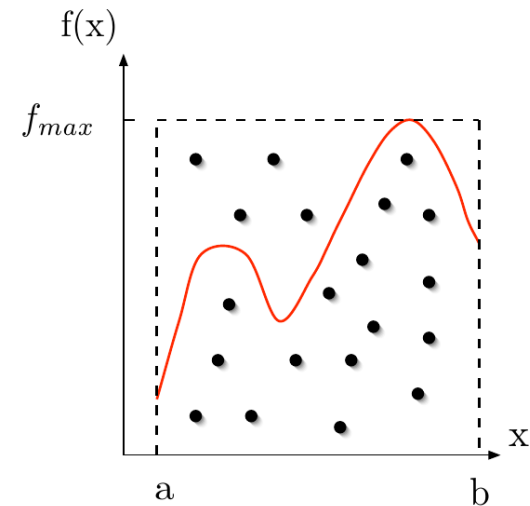
Hit and Miss method : Function



The Hit and Miss Method for a function $f(x)$

We want to estimate

$$A = \int_a^b f(x) dx$$



$$A_{estimate} = \frac{N_a}{N} f_{max} (b - a)$$

1. N points uniformly chosen within the square
2. N_a : number of points that “fall” under $f(x)$
3. The probability to fall below the curve is $p_a \simeq \frac{N_a}{N}$

The following is true

$$\lim_{N \rightarrow \infty} A_{estimate} = A \quad \lim_{N \rightarrow \infty} p_a = p$$

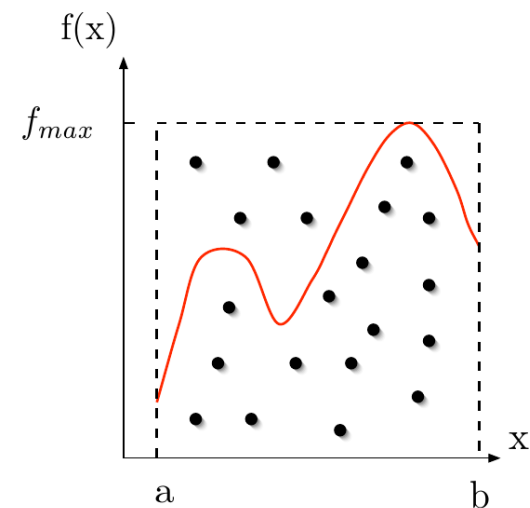
but the convergence is **very slow** , you need a lot of points N

Hit and Miss Method



The blind archer

An archer is throwing uniformly and randomly arrows in points (x_i, y_i) on the plane



1. if $y_i \leq f(x_i) \rightarrow$ YES (0)
2. if $y_i > f(x_i) \rightarrow$ NO (1)
3. This is a **Bernoulli process** with probability p
4. We perform N times the random experiment to throw arrows on the plane
 $(x_1, y_1), (x_2, y_2), (x_3, y_3) \dots (x_N, y_N)$
and N_a times we will be below the curve $f(x)$.
5. N_a is random and follows a **binomial distribution**
 - (a) average pN
 - (b) standard deviation $\sqrt{Np(1-p)}$

Hit and Miss Method



The blind archer

The estimate of the area below the function $f(x)$ is also a **random variable**

$$A_{estimate} = \frac{N_a}{N} f_{max}(b - a)$$

1. Average $\langle A_{estimate} \rangle = p f_{max}(b - a)$
2. Standard Deviation $\sigma_A = \frac{\sqrt{Np(1-p)}}{N} f_{max}(b - a) = \sqrt{\frac{p(1-p)}{N}} f_{max}(b - a)$

The error is decreasing as $1/\sqrt{N}$ with the number of trials N , as expected from the **Central Limit Theorem** and the $A_{estimate}$ will be distributed for different realizations of the random sequence of the points as a **Gaussian distribution** with average $\bar{A}_{estimate}$ and standard deviation σ_A .

Blind Archer → Random generator

Hit and Miss method



```
# Integration of a function with Hit and Miss Method
import numpy as np                # import the library as "np"

def HM(f, a, b, fmax):
    #
    somme = 0.
    i = 0
    while i < HM.N:
        x = np.random.random_sample() # the blind archer
        y = np.random.random_sample() # the blind archer
        xi = (b-a)*x+a                # random number in [a,b]
        fi = f(xi)                    # value of the function in xi
        if fi > fmax*y :
            somme += 1
        i += 1
    somme /= float(HM.N)              # probability p
    area = somme*fmax*(b-a)           # average area
    HM.erreur = np.sqrt(somme*(1-somme)/float(HM.N))*fmax*(b-a)
    #standard deviation on the average
    return area
```

Hit and Miss method



```
def f1(x):          # the function
    return x**4

# we can estimate the area over many realizations N
for N in [1e2, 1e3, 1e4]:
    print "N =", N
    HM.N = N
    print ("I1 = ", HM(f1, 0, 1,1), "+/-", HM.erreur, "(exact : 1/5)")
```

Idle HitandMiss.py

Uniform Sampling



We consider again the integral

$$I = \int_a^b f(x) dx$$

but we rewrite it as

$$I = \int_a^b G(x)p(x)dx = \langle G \rangle_p \quad \text{with} \quad p(x) = \frac{1}{(b-a)} \quad G(x) = (b-a)f(x)$$

where $p(x)$ is the uniform probability distribution function on the interval $[a, b]$, please notice that $\int_a^b p(x)dx = 1$

As already previously explained $I = \langle G \rangle_p$ is the **average** of the function $G(x)$ with respect to the random variable x uniformly distributed in $[a, b]$:

$$x = a + (b - a) * r \quad r \in [0, 1]$$

r can be generated with `np.random.random_sample()` in $[0, 1]$.

Uniform Sampling



Practical Implementation

We employ the random generator and we produce a sequence of N random numbers (x_1, x_2, \dots, x_N) from these we can compute the mean the variance of G

$$\langle G \rangle = \frac{1}{N} \sum_{i=1}^N G(x_i)$$

$$\sigma_N^2(G) = \frac{1}{N} \sum_{i=1}^N G^2(x_i) - \left(\frac{1}{N} \sum_{i=1}^N G(x_i) \right)^2$$

and from these the integral with the error on the average

$$I = \langle G \rangle \pm \frac{\sigma_N(G)}{\sqrt{N}}$$

in terms of the original function f this becomes finally

$$I = (b - a) \left[\langle f \rangle \pm \frac{\sigma_N(f)}{\sqrt{N}} \right]$$

the error on the integral decreases as $1/\sqrt{N}$

Generalization to higher dimensions



The uniform sampling Montecarlo method can be easily generalized to estimate integrals in dimension larger than one.

In general, if R is a region in d dimensions with a volume V_R , the integral is given by

$$\int_R d^d x f(\vec{x}) \approx \frac{V_R}{N} \sum_{i=1}^N f(\vec{x}_i).$$

where $\vec{x}_i = (x_i^{(1)}, x_i^{(2)}, \dots, x_i^{(d)}) \in R$ is a random vector, where each component is uniformly distributed.

In two dimensions ($d = 2$) the region $R = [a, b] \times [c, d]$ is a rectangle with « volume » $V_R = (b - a) \times (d - c)$. Therefore in 2d one has

$$\int_a^b \int_c^d dx dy f(x, y) \approx \frac{(b - a) \times (d - c)}{N} \sum_{i=1}^N f(x_i, y_i),$$

where (x_i, y_i) are random points uniformly distributed in R .

Comparison Monte Carlo and deterministic methods



The error for the MC method for any dimension remains $\propto \frac{1}{\sqrt{N}}$

Instead for the deterministic methods (quadrature) the error increases with the dimension d .

For **the method of the median point** the error was growing as $1/N^{2/d}$, therefore the Monte Carlo method becomes more efficient for

$$\frac{1}{2} > \frac{2}{d},$$

when

$$d > 4$$

For the Simpson method the MC method becomes more efficient for

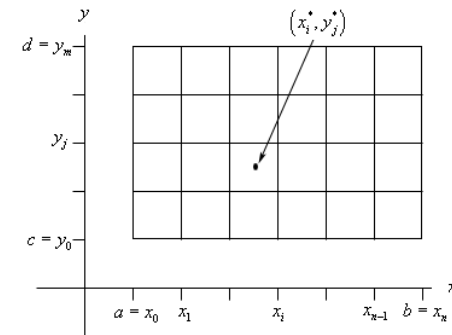
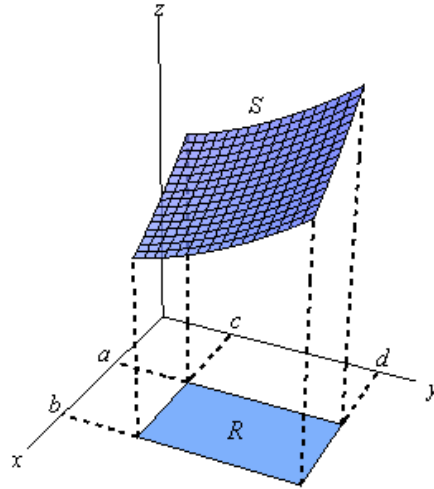
$$\frac{1}{2} > \frac{4}{d},$$

when

$$d > 8$$

and for the simple approximation, already for $d > 2$.

Method of the median point for 2 dimensions



We would like to integrate the two dimensional function $f(x, y)$ over the rectangle $R = [a, b] \times [c, d]$ with the method of the median point. As a first step we will divide the interval $[a, b]$ in N equidistant sub-intervals and $[c, d]$ in M equidistant sub-intervals, each of length

$$\Delta x = \frac{b - a}{N} \quad \Delta y = \frac{d - c}{M}$$

and with extrema $a_i := a + i \Delta x$, $b_i := a + (i + 1) \Delta x$, $c_j := c + j \Delta y$, $d_j := c + (j + 1) \Delta y$ for $i = 0, \dots, N - 1$ et $j = 0, \dots, M - 1$. Obviously, $a_0 = a$, $b_{N-1} = b$ and $a_{i+1} = b_i$; $c_0 = c$ and $d_{M-1} = d$.

Method of the median point for 2 dimensions



The method of the median point in 2d is given by :

$$\int_a^b dx \int_c^d dy f(x, y) \approx \Delta x \times \Delta y \sum_{i=0}^{N-1} \sum_{j=0}^{M-1} f(x_i^*, y_j^*) =: F_2^{2d}(N, M).$$

where $x_i^* = a + (i + \frac{1}{2}) \Delta x$ and $y_j^* = c + (j + \frac{1}{2}) \Delta y$

For the Simpson method, the expression in 2d is really complicated, see <http://mathfaculty.fullerton.edu/mathews/n2003/SimpsonsRule2DMod.html>

Exercise : Please estimate the following integral with the method of the median point and with the Monte Carlo method :

$$I_{2d} = \int_3^5 dx \int_2^9 dy (x^2 + 10y)$$

Method of the median point for 2 dimensions



$$\begin{aligned} I_{2d} &= \int_3^5 dx \int_2^9 dy (x^2 + 10y) = \int_2^9 dy \left[\frac{x^3}{3} + 10xy \right]_{x=3}^{x=5} = \\ &= \int_2^9 dy \frac{98}{3} + 20y = \left[\frac{98}{3}y + 10y^2 \right]_{y=2}^{y=9} = \frac{686}{3} + 770 \simeq 998.666 \end{aligned}$$

Summary



In summary the Monte Carlo method with **uniform sampling** is :

1. a very simple method
2. that converges for any dimension
3. but the method is not very efficient, because the points x_i [or $(x_i, y_i), \dots$] are not selected with regards to their weight (that is, their “importance”...) in the integral !

We need a better sampling !